

# Brushless DC-Flat Motors

External rotor technology, with housing

112 mNm  
60 W

## Series 4221 ... BXT H

Values at 22°C and nominal voltage	4221 G	018 BXT H	024 BXT H	048 BXT H		
1 Nominal voltage	$U_N$	18	24	48	V	
2 Terminal resistance, phase-phase	$R$	0,46	0,74	2,6	$\Omega$	
3 Efficiency, max.	$\eta_{max}$	88	87	88	%	
4 No-load speed	$n_0$	5 710	6 040	6 070	min <sup>-1</sup>	
5 No-load current, typ. (with shaft $\varnothing$ 5 mm)	$I_0$	0,177	0,139	0,103	A	
6 Starting torque	$M_A$	1 170	1 220	1 390	mNm	
7 Speed constant	$k_n$	320	253	127	min <sup>-1</sup> /V	
8 Back-EMF constant	$k_E$	3,13	3,95	7,87	mV/min <sup>-1</sup>	
9 Torque constant	$k_M$	29,8	37,7	75,2	mNm/A	
10 Current constant	$k_I$	0,0335	0,0265	0,0133	A/mNm	
11 Slope of n-M curve	$\Delta n/\Delta M$	4,93	4,97	4,4	min <sup>-1</sup> /mNm	
12 Terminal inductance, phase-phase	$L$	396	664	2 550	$\mu$ H	
13 Mechanical time constant	$\tau_m$	3,56	3,59	3,18	ms	
14 Rotor inertia	$J$	69	69	69	gcm <sup>2</sup>	
15 Angular acceleration	$\alpha_{max}$	169	177	201	$\cdot 10^3$ rad/s <sup>2</sup>	
<b>16 Operating temperature range:</b>						
– motor		-40 ... +100			°C	
– winding, max. permissible		+125			°C	
17 Shaft bearings		ball bearings, preloaded				
<b>18 Shaft load max.:</b>						
– with shaft diameter		5				mm
– radial at 3 000 min <sup>-1</sup> (5 mm from mounting flange)		25				N
– axial at 3 000 min <sup>-1</sup> (push / pull)		4				N
– axial at standstill (push / pull)		50				N
<b>19 Shaft play:</b>						
– radial		≤ 0,015				mm
– axial		= 0				mm
20 Mass		142				g
21 Direction of rotation		electronically reversible				
22 Speed up to	$n_{max}$	10 000				min <sup>-1</sup>
23 Number of pole pairs		7				
24 Hall sensors		digital				
25 Magnet material		NdFeB				
<b>Rated values for continuous operation</b>						
26 Rated torque	$M_N$	102	112	107	mNm	
27 Rated current (thermal limit)	$I_N$	3,33	2,87	1,39	A	
28 Rated speed	$n_N$	3 980	4 380	4 700	min <sup>-1</sup>	
29 Rated slope of n-M curve	$\Delta n/\Delta M$	17	14,8	12,8	min <sup>-1</sup> /mNm	

**Note:** Rated values are measured at nominal voltage and 22°C ambient temperature.

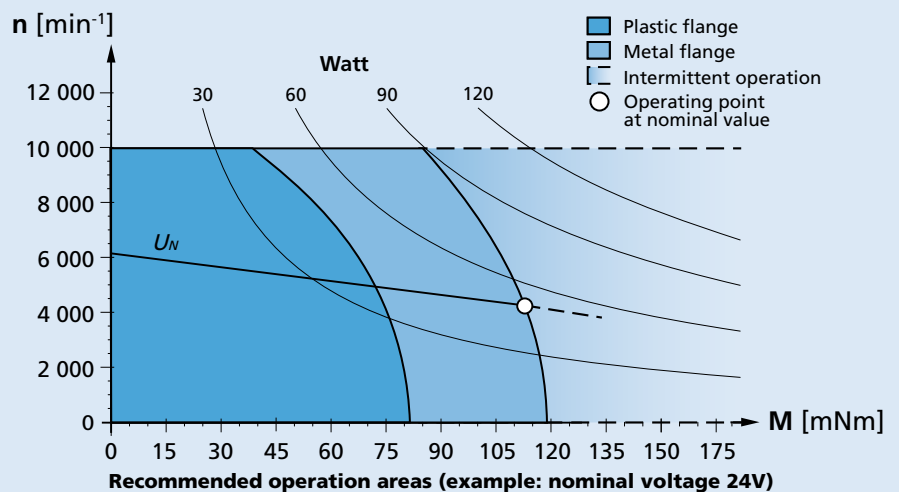
**Note:**

The display shows the range of possible operation points of the drives at a given ambient temperature of 22°C.

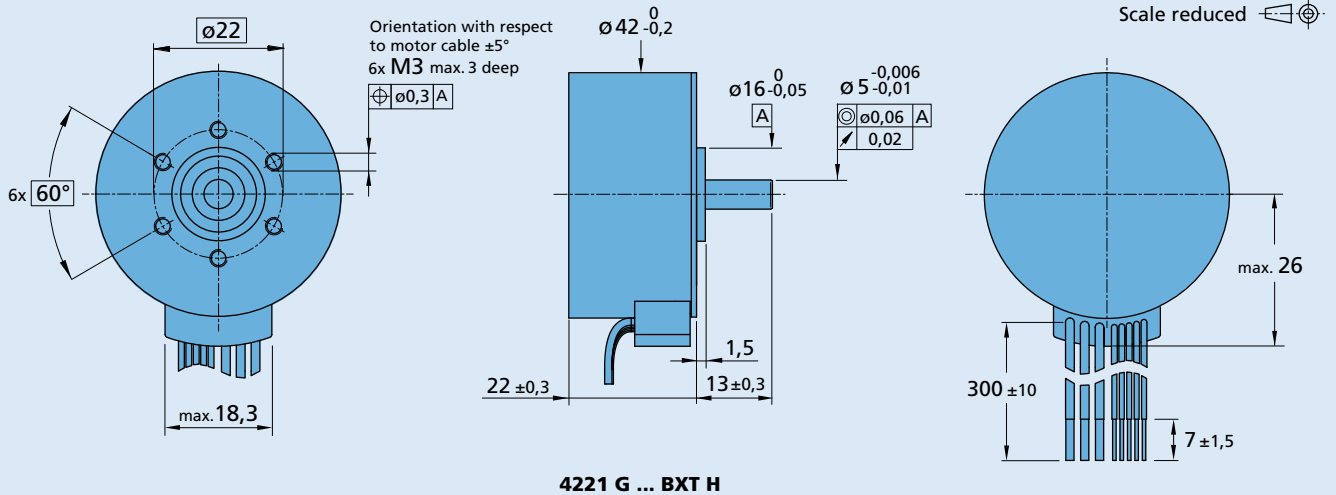
The diagram indicates the recommended speed in relation to the available torque at the output shaft.

It includes the assembly on a plastic- as well as on a metal flange (assembly method: IM B 5).

The nominal voltage linear slope describes the maximal achievable operating points at nominal voltage. Any points of operation above this linear slope will require a supply voltage  $U_{mot} > U_N$ .




### Dimensional drawing



### Option, cable and connection information

Example product designation: **4221G018BXTH-3830**

Option	Type	Description	Connection		
			No.	Function	Colour
3830		Standard cable with connector MOLEX Microfit 3.0, 43025-0800, recommended mating connector 43020-0800	1	Phase C	yellow
			2	Phase B	orange
			3	Phase A	brown
			4	GND	black
			5	U <sub>DD</sub> (+5V)	red
			6	Hall sensor C	grey
			7	Hall sensor B	blue
			8	Hall sensor A	green
			<b>Standard cable</b> Single wires, material PVC, AWG 20, Phase A/B/C, AWG 26, Hall A/B/C, U <sub>DD</sub> , GND		

### Product combination

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
38/1 38/1 S 38/2 38/2 S 42GPT	IE3-1024 IE3-1024 L IEF3-4096 IEF3-4096 L IERS3-500 IERS3-500 L IER3-10000 IER3-10000 L	SC 2804 S SC 5004 P SC 5008 S MC 3603 S MC 5004 P MC 5005 S	PMB32  To view our large range of accessory parts, please refer to the "Accessories" chapter.