

## Encoders

magnetic Encoder, digital outputs,  
3 channels, 1 - 1024 lines per revolution

For combination with  
Brushless DC-Motors  
DC-Micromotors  
Stepper Motors

### Series IE3-1024

		IE3-32	IE3-64	IE3-128	IE3-256	IE3-512	IE3-1024	
Lines per revolution	$N$	32	64	128	256	512	1 024	
Frequency range, up to <sup>1)</sup>	$f$	15	30	60	120	240	430	kHz
Signal output, square wave		2+1 Index						Channels
Supply voltage <sup>2)</sup>	$U_{DD}$	4,5 ... 5,5						V
Current consumption, typical <sup>3)</sup>	$I_{DD}$	typ. 20, max. 30						mA
Output current, max. <sup>4)</sup>	$I_{OUT}$	4						mA
Index Pulse width <sup>5)</sup>	$P_0$	90 ± 45						°e
Phase shift, channel A to B <sup>5)</sup>	$\Phi$	90 ± 45						°e
Signal rise/fall time, max. ( $C_{LOAD} = 50$ pF)	$tr/tf$	0,1 / 0,1						µs
Inertia of sensor magnet	$J$	0,08						gcm <sup>2</sup>
Operating temperature range		-40 ... +100						°C
Accuracy, typ.		0,5						°m
Repeatability, typ.		0,1						°m
Hysteresis		0,17						°m
Edge spacing, min.		421						ns
Mass, typ.		13,5						g

<sup>1)</sup> Velocity (min<sup>-1</sup>) =  $f$  (Hz) x 60/ $N$

<sup>2)</sup> 3,0 ... 3,6 V optional available on request

<sup>3)</sup>  $I_{DD} = 5$  V: with unloaded outputs

<sup>4)</sup>  $U_{DD} = 5$  V: low logic level < 0,4 V, high logic level > 4,5 V: CMOS- and TTL compatible

<sup>5)</sup> At 5 000 min<sup>-1</sup>

#### For combination with Motor

Dimensional drawing A	<L1 [mm]	Dimensional drawing D	<L1 [mm]	Dimensional drawing I	<L1 [mm]
2214 ... BXT H	26,8	2444 ... B - K1838	55,3	DM40100R	38,9
3216 ... BXT H	28,7	3056 ... B - K1838	67,3	DM52100N	45,9
4221 ... BXT H	34,0	3564 ... B - K1838	75,3	DM52100R	45,9
		4490 ... B - K1838	100,3		
		4490 ... BS - K1838	100,3		
Dimensional drawing B	<L1 [mm]	Dimensional drawing E	<L1 [mm]		
2237 ... CXR	52,5	2232 ... BX4	50,2		
2264 ... BP4	79,1	2250 ... BX4	68,2		
3274 ... BP4	90,8				
Dimensional drawing C	<L1 [mm]	Dimensional drawing F	<L1 [mm]		
2342 ... CR	60,5	3242 ... BX4	60,0		
2642 ... CXR	60,5	3268 ... BX4	86,0		
2642 ... CR	60,5				
2657 ... CXR	75,5	Dimensional drawing G	<L1 [mm]		
2657 ... CR	75,5	3863 ... CR - 2016	82,6		
2668 ... CR	86,5	3890 ... CR - 2016	108,6		
3242 ... CR	60,5				
3257 ... CR	75,5	Dimensional drawing H	<L1 [mm]		
3272 ... CR	90,5	AM3248	56,4		

#### Characteristics

These incremental encoders with 3 output channels, in combination with the FAULHABER Motors, are used for the indication and control of both shaft velocity and direction of rotation as well as for positioning.

A permanent magnet on the shaft creates a moving magnetic field which is captured using an angular sensor and further processed. At the encoder outputs, two 90° phase-shifted square wave signals are available with up to 1024 impulses and an index impulse per motor revolution.

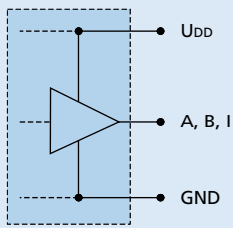
The encoder is available in a variety of different resolutions.

The encoder is connected with a ribbon cable.

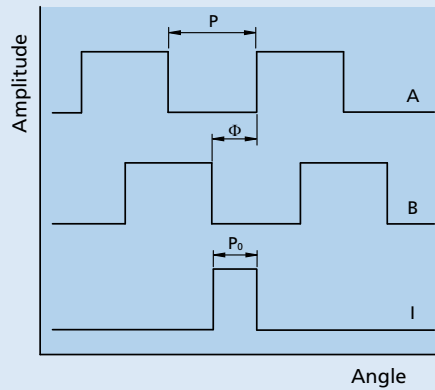
To view our large range of accessory parts, please refer to the "Accessories" chapter.

**Circuit diagram / Output signals**

**Output circuit**





**Output signals**  
with clockwise rotation as seen from the shaft end



**Connector information / Variants**

Example product designation: 2444S024B-K1838 IE3-1024

Option	Type	Description
3807	Connector 	for combination with DC-Motors series CR, CXR and with Brushless DC-Motor series B(S), BP4 and BXT H. Connector variants AWG 28 / PVC ribbon cable with connector MOLEX Picoblade 51021-0600, recommended mating connector 53047-0610.
3592	Connector 	for combination with Brushless DC-Motors series BX4. Connector variants AWG 28 / PVC ribbon cable with connector MOLEX Picoblade 51021-0600, recommended mating connector 53047-0610.
	Resolutions	Resolutions from 1 - 1024 lines per revolution are available by request.

**Connection Encoder**

**No. Function**

- 1 N.C.
- 2 Channel I
- 3 GND
- 4 U<sub>DD</sub>
- 5 Channel B
- 6 Channel A



**Standard cable**

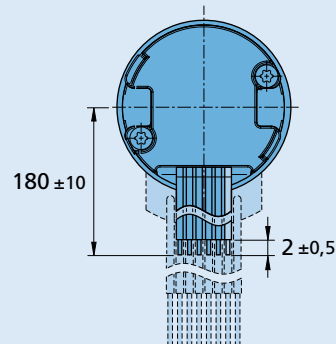
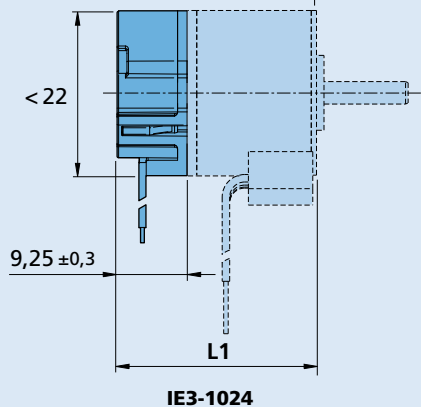
PVC-ribbon cable, 6-AWG 28, 1,27 mm

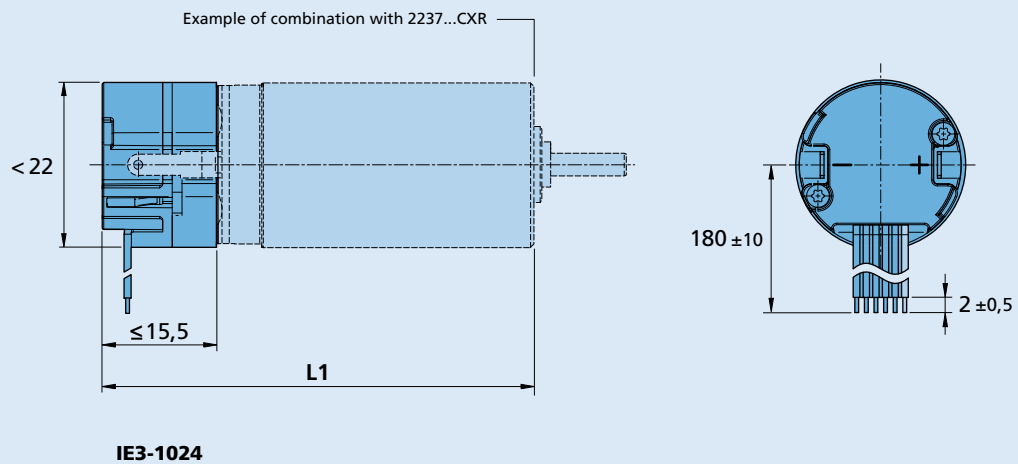
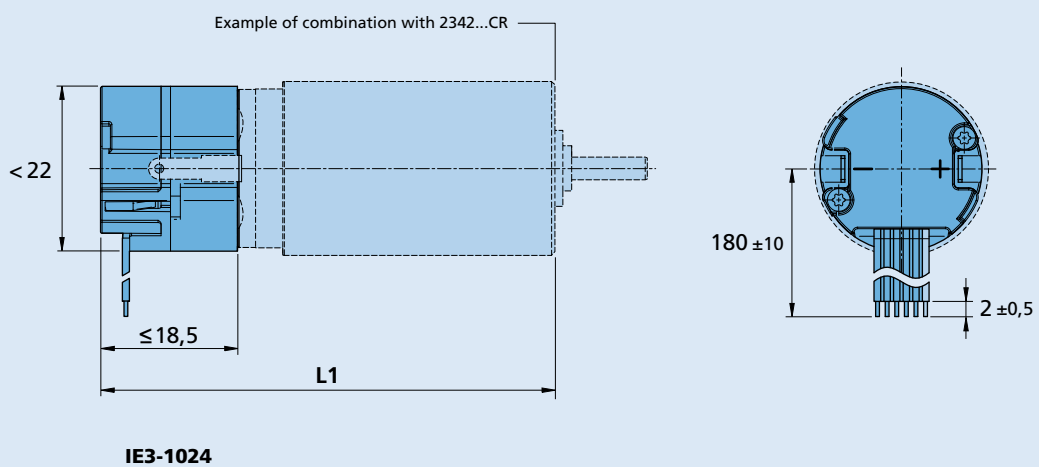
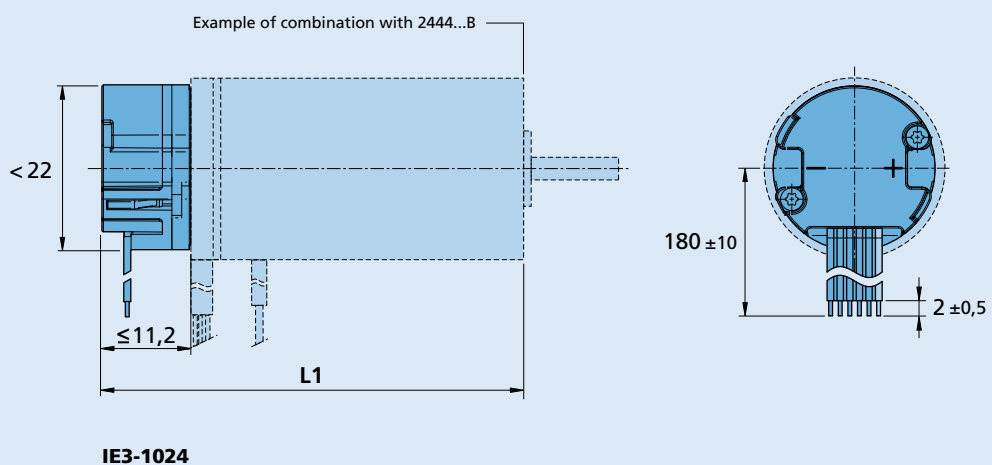
**Caution:**

Incorrect lead connection will damage the motor electronics!  
In combination with the BX4 brushless DC-servomotors with digital Hall sensors, the sensor supply connections of encoder and motor are connected to each other.

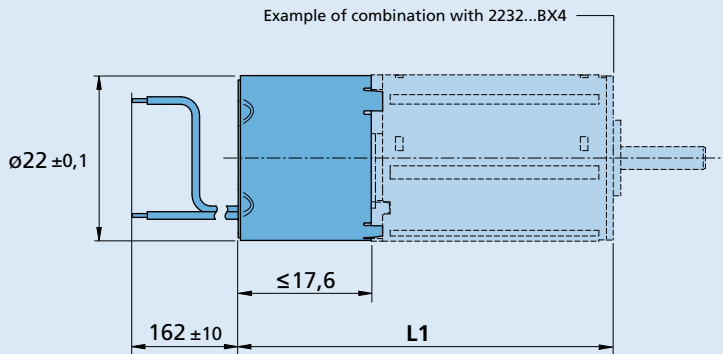
**Dimensional drawing A**

Example of combination with 2214...BXT H

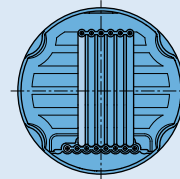


**Dimensional drawing B**

**Dimensional drawing C**

**Dimensional drawing D**


**Dimensional drawing E**



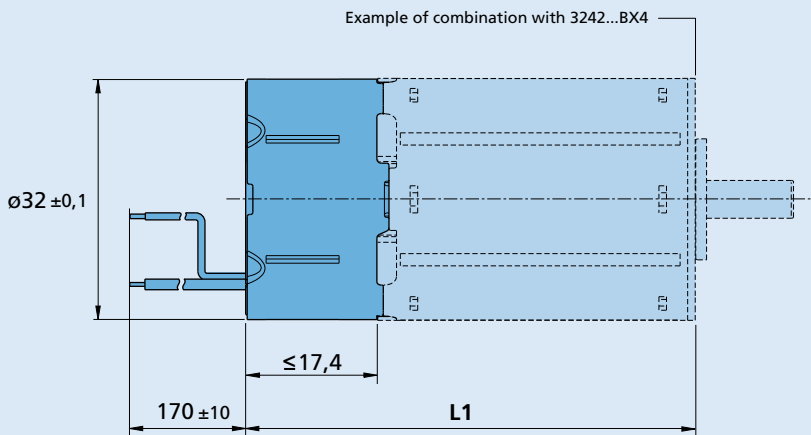
**Connection Encoder**



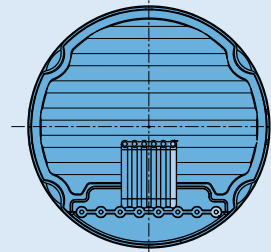
**Connection Motor**

**IE3-1024**

**Dimensional drawing F**



**Connection Encoder**

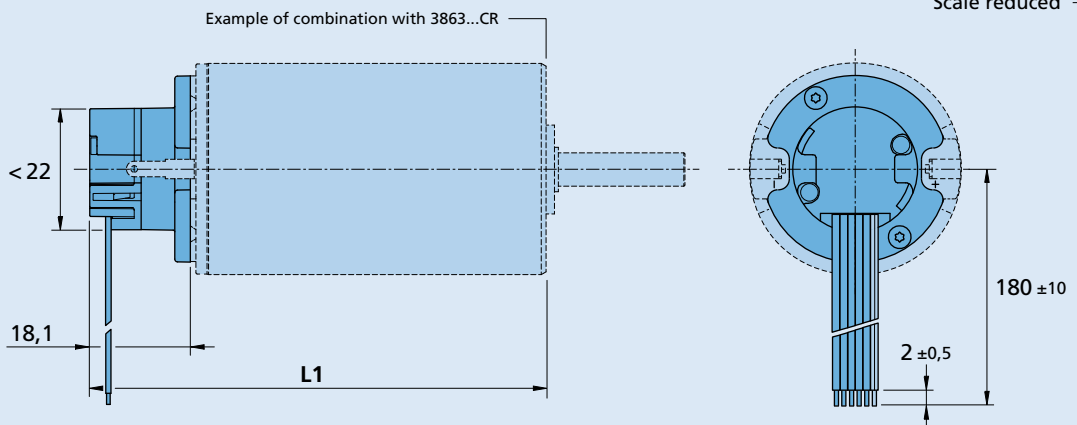


**Connection Motor**

**IE3-1024**

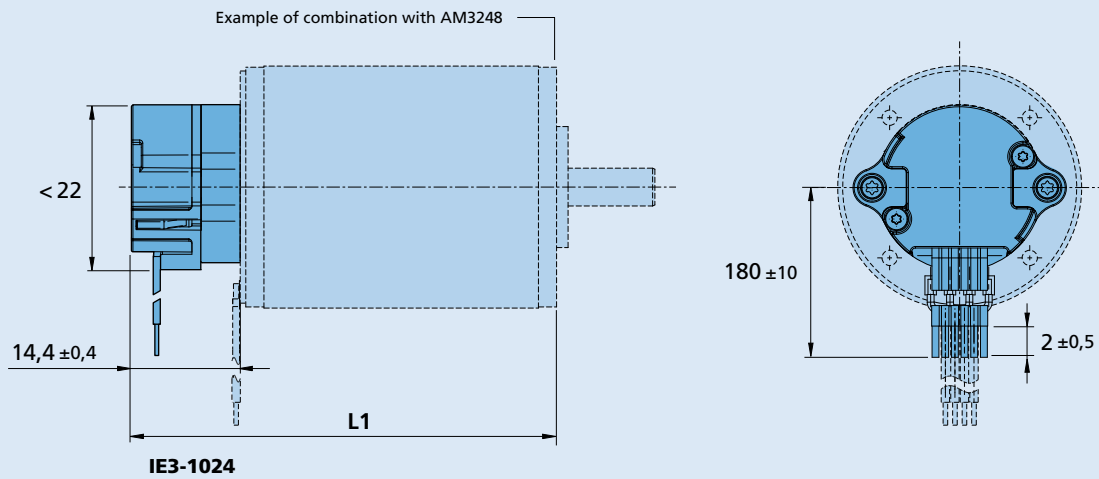
**Dimensional drawing G**

Scale reduced



**IE3-1024**

**Dimensional drawing H**



**Dimensional drawing I**

